

Construction of a Black Sea Bass fishery-independent sampling design using a simulation model and survey data

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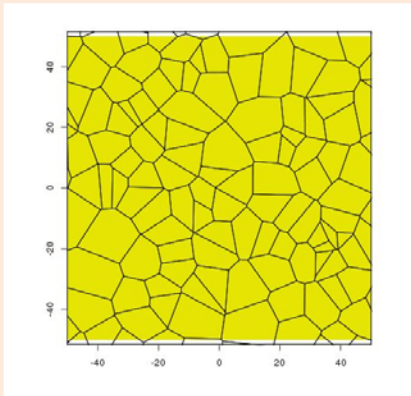
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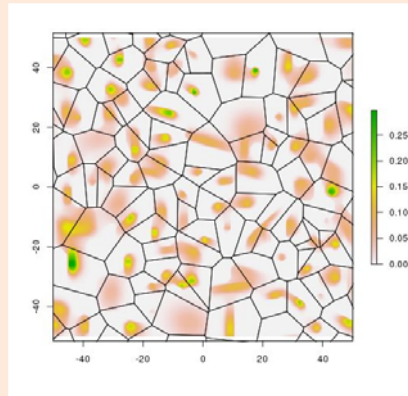
- The **objective** of this simulation analysis is to examine how sample allocation strategy effects the precision of population estimates and to use this information to refine Black Sea Bass survey design.

- The simulation consists of a number of components including:
 - Initialize the two-dimensional heterogeneous **spatial landscape** at two scales: the landscape and smaller patches.
 - Create particles that are the **target entities** of the sampling (the fish targeted in the simulation).
 - Construct **sampling units** used to estimate the fish density.

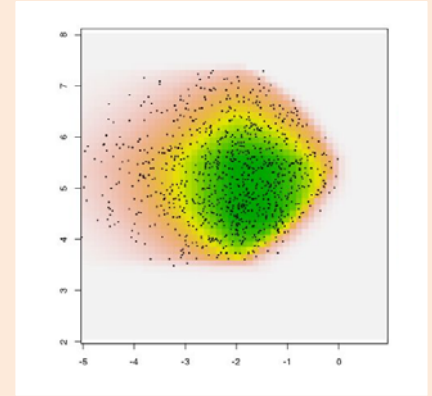
- A tessellation algorithm is used to divide the landscape into randomly placed and randomly sized patches ($n = 100$).
- Density of patches can be altered by the user.



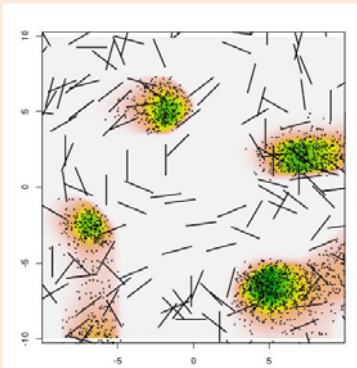
- Random parameter, bivariate skewed-normal distribution within patches determine the probability of occurrence of a particle at that location.
- The parameters that define the variance of the distribution control patchiness.



- Particles are assigned to the landscape based on probability set within a patch.
- Base model comprises 25 million particles that can occupy any of 1×10^{38} locations in the landscape.



- Trawls paths were constructed using rectangular polygons with an aspect ratio of width = 35 and a length of 2,000; a simulation of a 35 m wide trawl traveling over 2 km of fishing ground.
- In the base model, polygon orientation is randomly assigned.
- Trawl tracks are polygons that are independent of the scale and orientation of the landscape grid.



Confronting the model with data

- The observed distribution and abundance of an organism is a conditional probability that is determined by its abundance, scale of aggregation, and availability to the sampling gear.
- To evaluate the adequacy of alternative sampling designs we will:
 - Compare the observed BSB distribution and abundance from the Supplemental Finfish Survey conducted in the mid-Atlantic Bight to that in the model base run.
 - Alter the parameters in the base model that control the distribution and abundance of particles to match that observed in the field survey. These parameters include:
 - Number of clusters of fish density
 - Number of trawls (samples)
 - Parameters to control the kurtosis and skew of the frequency of occurrence distributions
 - Number of particles
 - Trawl dimension as a fraction of the current grid extent what is the trawl length as a fraction of grid size
 - Derive a set of alternative sampling strategies that can be employed in future surveys.
 - Evaluate the ability of each of the alternative sampling strategies provide precision estimates of fish density.



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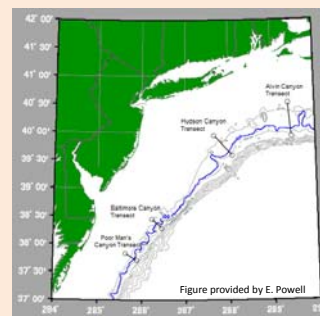


Figure provided by E. Powell

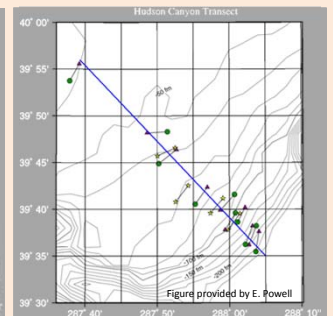


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